#### **Truss Testing Procedure**

This procedure will demonstrate how to use the force sensor, webcam and LoggerPro to test your truss design.

- 1. Change the Dual-Force Sensor to the +/- 50N setting. Attach the sensor to the part that fits over the truss.
- 2. Tie a loop in a string to attach to the hook. Cut the string about 6 in. longer then the distance between the hook and the shaft it will be attached to.
- 3. Push the string through a hole in the larger gear and tie a knot in the end of the string larger than the hole. Pull the string through until the knot is against the hole.
- 4. Wind the shaft to pull the excess slack out of the line. and





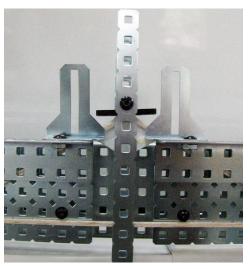




5. Make sure the spacer in the brace is turned such that a flat edge will be horizontal when pulling down. When testing Truss 1 it may also be helpful to place a Lock Bar between the top of the truss and the Standoff.



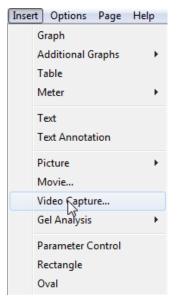




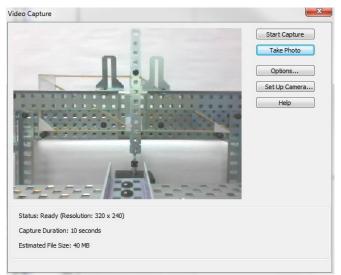
- 6. Connect the webcam and Golink! sensor to open USB ports.
- 7. Connect the Dual-Force Sensor to the GoLink! and open LoggerPro.
- 8. Hold the dual force sensor with the hook that connects to the brace unattached and Zero the sensor.

Бхр	eriment Data Analyze	Insert	Options
	Start Collection	<\$	pace>
	Store Latest Run		Ctrl+L
	Clear Latest Run		
	Кеер		Ctrl+K
	Extend Collection (15 s)		Ctrl+T
	Connect Interface		+
	Remove Interface		+
	Set Up Sensors		
	Add Offline Interface		÷.
	Data Collection	0	Otrl+D
	Remote		•
	Change Units		
	Calibrate		÷.
	Zero		Ctrl+0
1	Live Readouts		

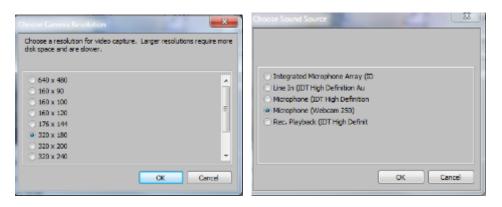
9. Choose Video Capture to set up the camera.



10. With the Webcam plugged in choose it on the next screen if there is more than one option, and the next screen should show the video from the Webcam. You may need to manually focus the Webcam.



11. Choose Set Up Camera (just under Options). You may need to choose the camera again. Choose 320x180 and click OK. Choose the Webcam's microphone. Choose Click OK.



12. Click the Options tab.

Start Capture
Take Photo
Options
Set Up Camera
Help

13. Make sure you have Video Capture with Sensor Data Collection chosen.

eo Capture Mode:	
· · ·	onized with Sensor Data Collection
Duration: 10 secor Sensor Sampling Inte	nos erval: 0.02 seconds/sample
Video Capture Only	
Capture Duration:	10 seconds v
Time-Lapse Capture:	
Capture Interval: 5	▼ seconds ▼ between frames

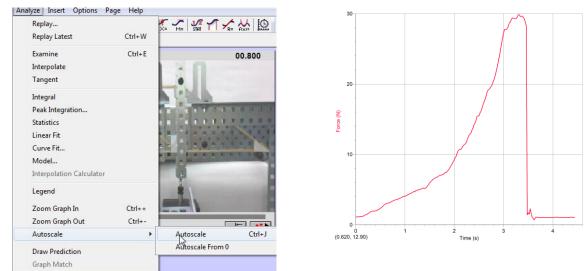
14. Take a photo using the Take Photo function to capture an image of the truss before breaking it.



15. Your team is now ready to test the truss. Remember you have 10 seconds, which may or may not seem like a lot of time. One person should be responsible for

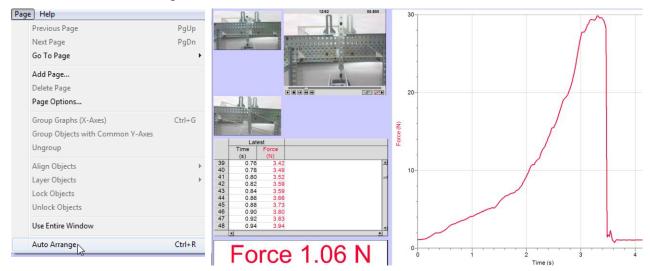
steadily cranking the string tight. Another person should start and stop the video capture and relay the time in seconds to the person breaking the truss. If you want to try it once, break a piece of scrap balsa. Your test should only have one major break, i.e. if the top breaks the test is completed; do not continue to break other portions of the truss.

16. Take a photo of the failed truss. Your file should have the graph, video and before and after pictures as shown below. Be sure to save.



17. Use Autoscale graph to zoom in on the graph.

18. Use Auto Arrange to be able to see all the elements on the screen.



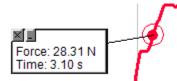
19. You can use the Replay feature to watch the video synched with graph.

Ana	Iyze Insert Options	Page Help
	Replay	
	Replay Latest	Ctrl+W
	<b>.</b> .	0.1.5
<	Examine	Ctrl+E

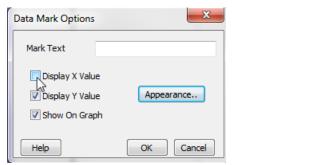
20. Use the examine button to observe forces at different places on the graph.

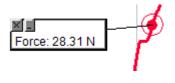


21. Using the examine function roll over the graph until the video frame is the last one before the truss failed and press the D key for Tag Data. This will label largest force on the graph before failure.



22. Double click on the box with the Tagged Data and uncheck the option to display X (Time) data.





23. Save your file in the location designated by your instructor.

24. Choose Print and include your name other information designated by your instructor. In printer properties change the orientation to landscape.